



Platinum Priority – Editorial

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The Learning Curve for Robot-assisted Partial Nephrectomy: There is Much Beyond a Trifecta

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In this issue of *European Urology*, Larcher and colleagues [1] report on the learning curve for robot-assisted partial nephrectomy (RAPN). The authors are to be congratulated for focusing for the first time on a more detailed analysis of the learning curve for this surgical technique. Using the statistical approach introduced by Vickers et al. [2] for urologic research, they found a nonlinear learning curve with respect to warm ischaemia time (WIT) with a plateau at 150 cases, and a linear learning curve in terms of the incidence of major complications (Clavien–Dindo grade >2). The rate of positive margins did not prove to be a significant parameter in describing the RAPN learning curve.

We were lucky to benefit from Andrew Vickers' knowledge when analysing the learning curve for laparoscopic and open radical prostatectomy [3,4]. Interestingly, we were able to use the rate of positive margins as a significant parameter, with a plateau occurring after 250 cases, whereas there was a negative linear correlation with respect to the rate of biochemical recurrence (BCR), even after 750 cases. This underlines the technical difficulty of both procedures. Use of the Da Vinci device may shorten the learning curve for laparoscopic radical prostatectomy (100 vs 300 cases to plateau) [5]. However, at least 150 RAPN cases were necessary to achieve a plateau for WIT [1].

However, we have to look beyond such an analysis. First, we have to define adequate parameters. Whereas a decrease in the positive margin rate may be useful for radical prostatectomy, it is not for PN, which is not surprising owing to the low incidence and minor clinical relevance. Vickers et al. [6] recently presented a feedback system for surgeon performance for radical prostatectomy

that includes various endpoints, such as BCR, functional outcome, positive margin rate, operating room time, complication rate, and estimated blood loss. Such multi-modal feedback may allow each surgeon to assess their personal performance status and the system should prompt undertaking of educational activities on an individual level. We think that this might be more useful rather than just focussing on the need for high-volume centres. Of course, as in the training and assessment of pilots, such outcome reporting has to be private to prevent the perception that feedback is punitive [7].

Apart from this, we should strive to better understand how surgeons improve in performance. It seems remarkable that we continue to spend billions of research dollars on looking at cancer cells on all levels but virtually nothing on looking at the surgeon's hands. Simulation, virtual reality training, and 3D-printed models might improve our understanding of patient anatomy and thus outcomes after surgery. It is interesting that most of the new tools are video-based and might not be applicable for open surgery [8].

Conflicts of interest: The authors have nothing to disclose.

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